# S SCHMERSAL

EN	Operating instructions	pages	1	to	6
----	------------------------	-------	---	----	---

$\mathbf{c}$	^	n	to	'n	4

1.2 1.3 1.4 1.5 1.6	Function	1 1 1 2
2.2 2.3 2.4	Product descriptionOrdering code2Special versions2Purpose2Technical data2Classification3	2
	Mounting General mounting instructions	
<b>4</b> 4.1	Electrical connection General information for electrical connection	3
5.2	Operating principle and settings LED functions	3
	Set-up and maintenance Functional testing	
	Disassembly and disposal Disassembly	

8	Αpı	pen	dix
•	, .P	,,,,	

8.1	Wiring examples	. 4
	Start configuration (with edge detection)	
8.3	Sensor configuration	. 5
R 4	Actuator configuration	E

#### 9 EU Declaration of conformity

# 1. About this document

#### 1.1 Function

This operating instructions manual provides all the information you need for the mounting, set-up and commissioning to ensure the safe operation and disassembly of the safety-monitoring module. The operating instructions must be available in a legible condition and a complete version in the vicinity of the device.

# 1.2 Target group: authorised qualified personnel

All operations described in this operating instructions manual must be carried out by trained specialist personnel, authorised by the plant operator only.

Please make sure that you have read and understood these operating instructions and that you know all applicable legislations regarding occupational safety and accident prevention prior to installation and putting the component into operation.

The machine builder must carefully select the harmonised standards to be complied with as well as other technical specifications for the selection, mounting and integration of the components.

# 1.3 Explanation of the symbols used



# Information, hint, note:

This symbol is used for identifying useful additional information.



**Caution:** Failure to comply with this warning notice could lead to failures or malfunctions.

**Warning:** Failure to comply with this warning notice could lead to physical injury and/or damage to the machine.

# 1.4 Appropriate use

The products described in these operating instructions are developed to execute safety-related functions as part of an entire plant or machine. It is the responsibility of the manufacturer of a machine or plant to ensure the correct functionality of the entire machine or plant.

The safety-monitoring module must be exclusively used in accordance with the versions listed below or for the applications authorised by the manufacturer. Detailed information regarding the range of applications can be found in the chapter "Product description".



To avoid EMC disturbances, the physical ambient and operational conditions at the place where the product is installed, must meet the provisions laid down in the paragraph "Electromagnetic Compatibility (EMC)" of EN 60204-1.

# 1.5 General safety instructions

The user must observe the safety instructions in this operating instructions manual, the country specific installation standards as well as all prevailing safety regulations and accident prevention rules.



Further technical information can be found in the Schmersal catalogues or in the online catalogue on the Internet: www.schmersal.net.

The information contained in this operating instructions manual is provided without liability and is subject to technical modifications.

# Operating instructions Safety-monitoring module

There are no residual risks, provided that the safety instructions as well as the instructions regarding mounting, commissioning, operation and maintenance are observed.

#### 1.6 Warning about misuse



In case of inadequate or improper use or manipulations of the safety-monitoring module, personal hazards or damage to machinery or plant components cannot be excluded. The relevant requirements of the standards ISO 14119 and ISO 13850 must be observed.

#### 1.7 Exclusion of liability

We shall accept no liability for damages and malfunctions resulting from defective mounting or failure to comply with this operating instructions manual. The manufacturer shall accept no liability for damages resulting from the use of unauthorised spare parts or accessories.

For safety reasons, invasive work on the device as well as arbitrary repairs, conversions and modifications to the device are strictly forbidden; the manufacturer shall accept no liability for damages resulting from such invasive work, arbitrary repairs, conversions and/or modifications to the device.

The safety-monitoring module must only be used when the enclosure is closed, i.e. with the front cover fitted.

#### 2. Product description

#### 2.1 Ordering code

This operating instructions manual applies to the following types:

#### SRB 301AN



Only if the information described in this operating instructions manual are realised correctly, the safety function and therefore the compliance with the Machinery Directive is maintained

#### 2.2 Special versions

For special versions, which are not listed in the order code below 2.1, these specifications apply accordingly, provided that they correspond to the standard version.

# 2.3 Purpose

The safety-monitoring modules for integration in safety circuits are designed for fitting in control cabinets. They are used for the safe evaluation of the signals of positive break position switches or magnetic safety sensors for safety functions on sliding, hinged and removable safety guards as well as emergency stop control devices and AOPDs.

The safety function is defined as the opening of the enabling circuits 13-14, 23-24 and 33-34 when the input S21-S22 is opened and/or when the input S13-S14 is closed.

The safety-relevant current paths with the outputs contacts 13-14, 23-24 and 33-34 meet the following requirements under observation of a PFH value assessment (also refer to chapter 2.5 "Safety classification"):

- Control category 4 PL e to ISO 13849-1
- SIL 3 to IEC 61508-2
- SILCL 3 to IEC 62061

To determine the Performance Level (PL) to ISO 13849-1 of the entire safety function (e.g. sensor, logic, actuator), an assessment of all relevant components is required.



The entire concept of the control system, in which the safety component is integrated, must be validated to the relevant standards.

# 2.4 Technical data

Material of the housings: Plastic, glass-fibre reinforced thermoy ver Material of the contacts: AgSnO, self-cleaning, positive Weight:  Start conditions: Automatic or start Feedback circuit (Y/N): Pull-in delay for automatic start: typ. 1 Pull-in delay with reset button: typ. Drop-out delay in case of emergency stop: typ. 15 ms, max. Bridging in case of voltage drops: typ. Mechanical data:  Connection type: Screw control Cable section: min. 0,25 mm² / max. 2,	61508 8-2-78 60715 0947-1 blastic, ntilated e drive 230 g button Yes 70 ms 25 ms
Climate resistance:  Mounting:  Snaps onto standard DIN rail to EN Terminal designations:  Material of the housings:  Plastic, glass-fibre reinforced thermop ver Material of the contacts:  AgSnO, self-cleaning, positive Weight:  Start conditions:  Automatic or start Feedback circuit (Y/N):  Pull-in delay for automatic start:  Pull-in delay with reset button:  Drop-out delay in case of emergency stop:  Bridging in case of voltage drops:  Mechanical data:  Connection type:  Screw conr Cable section:  MIEC 60  AgSnO, self-cleaning, positive ver  Automatic or start  typ. 1  Typ. 1  Typ. 1  Sup. 15 ms, max.  Screw conr  Screw conr  Cable section:  Min. 0,25 mm² / max. 2,	8-2-78 60715 0947-1 blastic, ntilated e drive 230 g button Yes 170 ms 25 ms
Mounting: snaps onto standard DIN rail to EN Terminal designations: IEC 60 Material of the housings: Plastic, glass-fibre reinforced thermop ver Material of the contacts: AgSnO, self-cleaning, positive Weight:  Start conditions: Automatic or start Feedback circuit (Y/N): Pull-in delay for automatic start: typ. 1 Pull-in delay with reset button: typ. Drop-out delay in case of emergency stop: typ. 15 ms, max. Bridging in case of voltage drops: typ. Mechanical data:  Connection type: Screw conr Cable section: min. 0,25 mm² / max. 2,	60715 0947-1 blastic, ntilated e drive 230 g button Yes 170 ms 25 ms
Terminal designations:  Material of the housings:  Plastic, glass-fibre reinforced thermop ver  Material of the contacts:  AgSnO, self-cleaning, positive  Weight:  Start conditions:  Automatic or start  Feedback circuit (Y/N):  Pull-in delay for automatic start:  Pull-in delay with reset button:  Drop-out delay in case of emergency stop:  Bridging in case of voltage drops:  Mechanical data:  Connection type:  Screw conr  Cable section:  Plastic, glass-fibre reinforced thermop  ver  AgSnO, self-cleaning, positive  typ. 19  Automatic or start  typ. 19  Lyp.	0947-1 blastic, htilated e drive 230 g button Yes 70 ms 25 ms
Material of the housings: Plastic, glass-fibre reinforced thermopy ver Material of the contacts: AgSnO, self-cleaning, positive Weight:  Start conditions: Automatic or start Feedback circuit (Y/N): Pull-in delay for automatic start: typ. 1 Pull-in delay with reset button: typ. Drop-out delay in case of emergency stop: typ. 15 ms, max. Bridging in case of voltage drops: typ. Mechanical data:  Connection type: Screw conrection contacts of the more reinforced thermopy very description.	olastic, ntilated e drive 230 g button Yes 70 ms 25 ms
ver  Material of the contacts: AgSnO, self-cleaning, positive Weight: Start conditions: Automatic or start Feedback circuit (Y/N): Pull-in delay for automatic start: typ. 1 Pull-in delay with reset button: typ. Drop-out delay in case of emergency stop: typ. 15 ms, max. Bridging in case of voltage drops: typ.  Mechanical data: Connection type: Screw conr Cable section: min. 0,25 mm² / max. 2,	e drive 230 g button Yes 70 ms 25 ms
Material of the contacts: AgSnO, self-cleaning, positive Weight:  Start conditions: Automatic or start Feedback circuit (Y/N):  Pull-in delay for automatic start: typ. 1  Pull-in delay with reset button: typ.  Drop-out delay in case of emergency stop: typ. 15 ms, max.  Bridging in case of voltage drops: typ.  Mechanical data:  Connection type: Screw conrection: min. 0,25 mm² / max. 2,	e drive 230 g button Yes 70 ms 25 ms
Weight:  Start conditions:  Automatic or start Feedback circuit (Y/N):  Pull-in delay for automatic start:  Pull-in delay with reset button:  Drop-out delay in case of emergency stop:  Bridging in case of voltage drops:  Wechanical data:  Connection type:  Cable section:  Automatic or start  typ. 1  typ. 1  typ. 15 ms, max.  typ. 15 ms, max.  Screw conr  in 0,25 mm² / max. 2,	230 g button Yes 70 ms 25 ms
Start conditions:  Feedback circuit (Y/N):  Pull-in delay for automatic start:  Pull-in delay with reset button:  Drop-out delay in case of emergency stop:  Bridging in case of voltage drops:  Wechanical data:  Connection type:  Cable section:  Automatic or start  typ. 1  typ. 1  typ. 15 ms, max.  typ.  Mechanical data:  Screw conr  Cable section:  Automatic or start	button Yes 70 ms 25 ms
Feedback circuit (Y/N):  Pull-in delay for automatic start: typ. 1  Pull-in delay with reset button: typ.  Drop-out delay in case of emergency stop: typ. 15 ms, max.  Bridging in case of voltage drops: typ.  Mechanical data:  Connection type: Screw conr  Cable section: min. 0,25 mm² / max. 2,	Yes 70 ms 25 ms
Pull-in delay for automatic start: typ. 1 Pull-in delay with reset button: typ. Drop-out delay in case of emergency stop: typ. 15 ms, max. Bridging in case of voltage drops: typ.  Mechanical data: Connection type: Screw conr Cable section: min. 0,25 mm² / max. 2,	25 ms
Pull-in delay with reset button: typ.  Drop-out delay in case of emergency stop: typ. 15 ms, max.  Bridging in case of voltage drops: typ.  Mechanical data:  Connection type: Screw conr Cable section: min. 0,25 mm² / max. 2,	25 ms
Drop-out delay in case of emergency stop: typ. 15 ms, max.  Bridging in case of voltage drops: typ.  Mechanical data:  Connection type: Screw conr Cable section: min. 0,25 mm² / max. 2,	
Bridging in case of voltage drops: typ.  Mechanical data:  Connection type: Screw conr Cable section: min. 0,25 mm² / max. 2,	
Connection type: Screw conr Cable section: min. 0,25 mm² / max. 2,	15 ms
Cable section: min. 0,25 mm² / max. 2,	
· · · · · · · · · · · · · · · · · · ·	nection
Connecting cable: rigid or f	5 mm <sup>2</sup>
	lexible
	).6 Nm
With removable terminals (Y/N):	No
Mechanical life: 10 million oper	
Electrical life: Derating curve available on r	
	11 ms
Resistance to vibration in 10 to 1	,
accordance with EN 60068-2-6: Amplitude 0.3	35 mm
Ambient conditions:  Ambient temperature: -25 °C	.60 °C
Ambient temperature: -25 °C · Storage and transport temperature: -40 °C ·	
Protection class: Enclosure	
Terminals	
Clearance	
Insulation values to IEC 60664-1: Basic ins	
Rated impulse withstand voltage U <sub>imp</sub> :	4 kV
Overvoltage category:	III
Degree of pollution:	2
EMC rating: to EMC Di	rective
Electrical data:	
Contact resistance in new state: max. 1	00 mΩ
Power consumption: max. 2.1 W /	
Rated operating voltage U <sub>e</sub> : 24 VDC –10%/	,
residual ripple max	
24 VAC –15%	
	60 Hz
Fuse rating for the operating voltage: Internal electronic trip, to	
current > 500 mA, reset after approx.  Monitored inputs:	i sec.
Cross-wire detection (Y/N):	Yes
Wire breakage detection (Y/N):	Yes
Earth leakage detection (Y/N):	Yes
Number of NO contacts:	1
Number of NC contacts:	<u>.</u>
Cable length: 1,500 m with1.	
2,500 m with2.	
	. 40 Ω
Outputs:	
Number of safety contacts:	3
Number of auxiliary contacts:	0
Number of signalling outputs:	1
Switching capacity of the safety contacts: 13-14, 23-24,	33-34:
max. 250 V, 6 A ohmic (inc	
in case of appropriate protective v	
min. 10 V /	
Switching capacity of the signalling outputs: Y1: 24 VDC / 1	υυ mA

# Operating instructions Safety-monitoring module

The data specified in this manual are applicable when the component is operated with rated operating voltage  $U_{\rm e}$   $\pm 0\%$ .



Use copper conductors only.
Use 60°C/75°C conductors.
Use 60/75°C wire only.
Use No. 28-12 AWG wire size only.

Tightening torque: 5 lb in.

#### 2.5 Classification

Standards:	ISO 13849-1, IEC 61508
PL:	up to e
Control Category:	up to 4
DC:	99% (high)
CCF:	> 65 points
PFH:	≤ 2.00 × 10 <sup>-8</sup> /h
SIL:	suitable for SIL 3 applications
Mission time:	20 years

The PFH value of  $2.00 \times 10^{-8}$ /h applies to the combinations of contact load (current through enabling contacts) and number of switching cycles  $(n_{\text{oply}})$  mentioned in the table below. At 365 operating days per year and a 24-hours operation, this results in the below-mentioned switching cycle times  $(t_{\text{cycle}})$  for the relay contacts. Diverging applications upon request.

Contact load	$n_{op/y}$	t <sub>cycle</sub>
20 %	525,600	1.0 min
40 %	210,240	2.5 min
60 %	75,087	7.0 min
80 %	30,918	17.0 min
100 %	12,223	43.0 min

# 3. Mounting

# 3.1 General mounting instructions

Mounting: snaps onto standard DIN rails to EN 60715.

Snap the bottom of the enclosure slightly tilted forwards in the DIN rail and push up until it latches in position.

#### 3.2 Dimensions

All measurements in mm.

Device dimensions (H/W/D): 100 x 22.5 x 121 mm

#### 4. Electrical connection

#### 4.1 General information for electrical connection



As far as the electrical safety is concerned, the protection against unintentional contact of the connected and therefore electrically interconnected apparatus and the insulation of the feed cables must be designed for the highest voltage, which can occur in the device.



The electrical connection may only be carried out by authorised personnel in a de-energised condition.

Wiring examples: see appendix

# 5. Operating principle and settings

#### 5.1 LED functions

- K1: Status channel 1
- K2: Status channel 2
- U<sub>i</sub>: Status internal operating voltage (LED is on, when the operating voltage on the terminals A1-A2 is ON and the fuse has not been triggered).

# 5.2 Description of the terminals

Voltages:	A1	+24 VDC/24 VAC
	A2	0 VDC/0 VAC
Inputs:	S13 - S14	Input channel 1
	S21 - S22	Input channel 2
Outputs:	13 - 14	First safety enabling circuit
	23 - 24	Second safety enabling circuit
	33 - 34	Third safety enabling circuit
	Y1	Signalling output
Start:	X1 - X2	Feedback circuit and external reset
		(monitored)
	X1 - X3	Automatic start



Fig. 1

# 5.3 Notes



Signalling outputs must not be used in safety circuits.



Due to the operating principle of the electronic fuse, the customer must check that no hazard is caused by an unexpected restart in circuits without reset button (automatic reset).

# 6. Set-up and maintenance

#### 6.1 Functional testing

The safety function of the safety-monitoring module must be tested. The following conditions must be previously checked and met:

- 1. Correct fixing
- 2. Check the integrity of the cable entry and connections
- 3. Check the safety-monitoring module's enclosure for damage.
- Check the electrical function of the connected sensors and their influence on the safety-monitoring module and the downstream actuators

#### 6.2 Maintenance

A regular visual inspection and functional test, including the following steps, is recommended:

- 1. Check the correct fixing of the safety-monitoring module
- 2. Check the cable for damages
- 3. Check electrical function



If a manual functional check is necessary to detect a possible accomulation of faults, then this must take place during the intervals noted as follows:

- at least every month for PL e with category 3 or category 4 (according to ISO 13849-1) or SIL 3 with HFT (hardware fault tolerance) = 1 (according to IEC 62061).
- at least every 12 months for PL d with category 3 (according to ISO 13849-1) or SIL 2 with HFT (hardware fault tolerance) = 1 (according to IEC 62061)

Damaged or defective components must be replaced.

# 7. Disassembly and disposal

# 7.1 Disassembly

The safety-monitoring module must be disassembled in a de-energised condition only.

Push up the bottom of the enclosure and hang out slightly tilted forwards.

#### 7.2 Disposal

The safety-monitoring module must be disposed of in an appropriate manner in accordance with the national prescriptions and legislations.

# 8. Appendix

# 8.1 Wiring examples

Dual-channel control, shown for a guard door monitor with two position switches where one has a positive break contact; with external reset button  $\[ \mathbb{R} \]$  (Fig. 2)

- Relay outputs: Suitable for 2-channel control, for increase in capacity or number of contacts by means of contactors or relays with positiveguided contacts.
- The control system recognises wire-breakage, earth faults and cross-wire shorts in the monitoring circuit.
- 🔫 = Feedback circuit

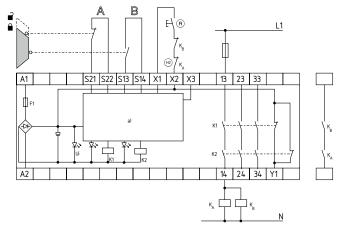


Fig. 2 a) Logic

# 8.2 Start configuration (with edge detection)

# External reset button (Fig. 3)

- The external reset button is integrated in the feedback circuit in series.
- The safety-monitoring module is activated upon actuation of the reset button

#### Automatic start (Fig. 4)

- The automatic start is programmed by connecting the feedback circuit to the terminals X1-X3. If the feedback circuit is not required, establish a bridge.
- Caution: Not admitted without additional measure due to the risk of gaining access by stepping behind!
- When the SRB 301AN safety-monitoring module is used with the operating mode "Automatic start", an automatic restart after a shutdown in case of emergency must be prevented by the upstream control to EN 60204-1 paragraph 9.2.5.4.2.



Due to the operating principle of the electronic fuse, the customer must check that no hazard is caused by an unexpected restart in circuits without reset button (automatic reset).



#### 8.3 Sensor configuration

# Dual-channel emergency stop circuit with command devices to ISO 13850 (EN 418) and IEC 60947-5-5 (Fig. 5)

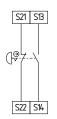
- Wire breakage and earth leakage in the control circuits are detected.
- · Cross-wire shorts between the control circuits are detected.
- Category 4 PL e to ISO 13849-1 possible.

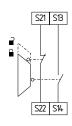
# Dual-channel guard door monitoring circuit with interlocking device to ISO 14119 (Fig. 6)

- · With at least one positive-break position switch
- Wire breakage and earth leakage in the control circuits are detected.
- Cross-wire shorts between the control circuits are detected.
- Category 4 PL e to ISO 13849-1 possible.

# Dual-channel control of magnetic safety switches to IEC 60947-5-3

- Wire breakage and earth leakage in the control circuits are detected.
- Cross-wire shorts between the monitoring circuits are detected.
- Category 4 PL e to ISO 13849-1 possible.





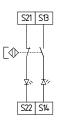


Fig. 5

Fig. 6

Fig. 7



The connection of magnetic safety switches to the SRB 301AN safety-monitoring module is only admitted when the requirements of the standard IEC 60947-5-3 are observed.

As the technical data are regarded, the following minimum requirements must be met:

- switching capacity: min. 240 mW
- switching voltage: min. 24 VDC
- switching current: min. 10 mA



For example, the following safety sensors meet the requirements:

- BNS 33-11Z, BNS 33-11ZG
- BNS 250-11Z, BNS 250-11ZG
- BNS 120-11Z
- BNS 180-11Z
- BNS 303-11Z, BNS 303-11ZG
- BNS 260-11Z, BNS 260-11ZG



When sensors with LED are wired in the control circuit (protective circuit), the following rated operating voltage must be observed and respected:

- 24 VDC with a max. tolerance of -5 %/+20 %
- 24 VAC with a max. tolerance of -5 %/+10 %

Otherwise availability problems could occur, especially in series-wired sensors, where a voltage drop in the control circuit is triggered by LEDs for instance.

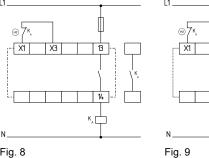
#### 8.4 Actuator configuration

#### Single-channel control (see Fig. 8)

- Suitable for increase in capacity or number of contacts by means of contactors or relays with positive-guided contacts.
- If the feedback circuit is not required, establish a bridge.
- (H2) = Feedback circuit

#### Dual-channel control with feedback circuit (Fig. 9)

- · Suitable for increase in capacity or number of contacts by means of contactors or relays with positive-guided contacts.
- If the feedback circuit is not required, establish a bridge.
- (H2) = Feedback circuit



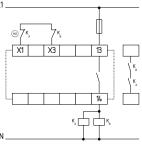


Fig. 8

# 9. EU Declaration of conformity

# **EU** Declaration of conformity

**9** SCHMERSAL

K.A. Schmersal GmbH & Co. KG Original

Möddinghofe 30 42279 Wuppertal Germany

Internet: www.schmersal.com

We hereby certify that the hereafter described components both in their basic design and construction conform

to the applicable European Directives.

Name of the component: SRB 301AN

Description of the component: Safety-monitoring module for emergency stop circuits, guard door

monitoring and magnetic safety switches

**Relevant Directives:** Machinery Directive 2006/42/EC

EMC-Directive 2014/30/EU RoHS-Directive 2011/65/EU

Applied standards: IEC 60947-5-1:2016 (in extracts),

IEC 60947-5-3:2013, ISO 13849-1:2015, ISO 13849-2:2012

Notified body for the prototype

TÜV Rheinland Industrie Service GmbH

Tund

Alboinstr. 56, 12103 Berlin

ID n°: 0035

EC-prototype test certificate: 01/205/5724.00/19

Person authorised for the compilation of the technical documentation:

Oliver Wacker Möddinghofe 30

42279 Wuppertal

Place and date of issue: Wuppertal, November 21, 2019

> Authorised signature Philip Schmersal Managing Director

SRB301AN-F-EN

The currently valid declaration of conformity can be downloaded from the internet at www.schmersal.net.





Möddinghofe 30, 42279 Wuppertal

Germany

Phone: +49 202 6474-0 Telefax: +49 202 6474-100 E-Mail: info@schmersal.com Internet: www.schmersal.com