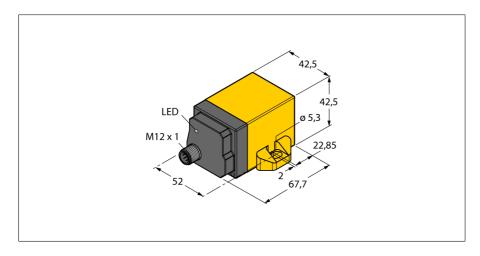


Inclinometer B2N360-Q42-E2LIUPN8X2-H1181



Туре	B2N360-Q42-E2LIUPN8X2-H1181		
ID	1534116		
Measuring principle	Acceleration		
General data			
Resolution	16 bit		
Measuring range	0360°		
Measuring range x-axis	0360°		
Measuring range y-axis	0360°		
Number of measuring axes	2		
Repeat accuracy	2 ≤ 0.07 % of full scale		
Nepeat accuracy			
Linearity deviation	depending on the filter setting ≤ 0.3 % of full scale, applies in the functional area of		
Linearity deviation	• • • • • • • • • • • • • • • • • • • •		
Tananan daiff	upper or lower hemisphere		
Temperature drift	≤ ± 0.015 %/K		
Electrical data			
Operating voltage	1530 VDC		
Residual ripple	≤ 10 % U _{ss}		
DC rated operational current	≤ 150 mA		
Isolation test voltage	≤ 0.5 kV		
Short-circuit protection	yes		
Wire breakage/Reverse polarity protection	yes/ Complete		
Communication protocol	IO-Link		
Output function	8-pin, NO/NC, PNP/NPN, analog output		
Voltage output	010 V		
Current output	020 mA		
·	programmable via IO-Link, e.g. 420 mA		
Load resistance voltage output	≥ 4.7 kΩ		
Load resistance current output	≤ 0.4 kΩ		
Sample rate	500 Hz		
Current consumption	< 60 mA at 24 VDC		
IO-Link specification	V 1.1		
Programming	FDT/DTM		
Frame type	2.2		

Yes

- Rectangular, plastic, PA12-GF30
- Status display via LEDs
- Parameterizable filter functions for different applications
- Parameterizable via teach pin
- Acceleration function ± 2 g, measuring range parameterizable
- 15...30 VDC
- Analog output
- Programmable current and voltage output functions
- Factory setting 4...20 mA
- All functions programmable via IO-Link/ PACTware
- Programmable NC/NO switch functions, available as NPN or PNP version
- Process value for x and y-axis in the 16-bit IO-Link telegram
- M12 × 1 connector, 8-pin
- Adapter cable RKC8.301T-1.5-RSC4T/ TXL320 required for IO-Link communication

Wiring Diagram





Functional principle

The TURCK inclinometers incorporate a micromechanical pendulum, operating on the principle of MEMS technology (Mikro Elektro Mechanic Systems).

The pendulum basically consists of two 'plate' electrodes arranged in parallel with a dielectric placed in the middle. When the sensor is inclined, the dielectric in the middle moves, causing the capacitance ratio between both electrodes to change.

The downstream electronics evaluates this change in capacitance and generates a corresponding output signal.

Included in the SIDI GSDML



Mechanical data		
Design	Rectangular, Q42	
Dimensions	67.7 x 42.5 x 42.5 mm	
Housing material	Plastic, PA12-GF30	
Electrical connection	Connector, M12 × 1	
Environmental conditions		
Ambient temperature	-25+85 °C	
	Acc. to UL approval to +70 °C	
Vibration resistance	55 Hz (1 mm)	
Shock resistance	30 g (11 ms)	
Protection class	IP68	
	IP69K	
MTTF	159 years acc. to SN 29500 (Ed. 99) 40 °C	
Power-on indication	LED, Green	
Switching state	LED, Yellow	



Programming instructions

Parameter	Teach input	LED indication
Zero point offset (see notes)	Bridge Pin 3 (GND) and Pin 8 for 5 s	Status LED (yellow) flashes, after 1 s steady, after 3 s
		flashes, after 5 s steady
Measuring range start, X-axis (see notes)	Bridge Pin 1 (U _B) and Pin 8 for 1 s	Status LED (green) flashes, after 1 s steady
Measuring range end, X-axis	Bridge Pin 1 (U _B) and Pin 8 for 3 s	Status LED (green) flashes, after 1 s steady, after 3 s
(see notes)		flashes
Measuring range start, Y-axis	Bridge Pin 3 (GND) and Pin 8 for 1 s	Status LED (yellow) flashes, after 1 s steady
(see notes)		
Measuring range end, Y-axis	Bridge Pin 3 (GND) and Pin 8 for 3 s	Status LED (yellow) flashes, after 1 s steady, after 3 s
(see notes)		flashes
Pre-set mode	Bridge Pin 1 (U _B) and Pin 8 for 10 s You must	Status LED (green) flashes, after 10 s steady
Angle	set a further teach input within 10 s or the de-	
	vice will automatically exit this mode	
-10° +10°	Bridge Pin 3 (GND) and Pin 8 once briefly	LED (yellow) flashes once
-45°+45°	Bridge Pin 3 (GND) and Pin 8 twice briefly	LED (yellow) flashes twice
-60°+60°	Bridge Pin 3 (GND) and Pin 8 three times briefly	LED (yellow) flashes three times
-85°+85°	Bridge Pin 3 (GND) and Pin 8 four times briefly	LED (yellow) flashes four times
Pre-set mode	Bridge Pin 1 (U _B) and Pin 8 for 10 s You must	Status LED (green) steady, after 10 s flashes
Function	set a further teach input within 10 s or the de-	
	vice will automatically exit this mode	
Mode 1 "Upper hemisphere," default setting	Bridge Pin 1 (U _B) and Pin 8 once briefly	LED (green) flashes once
Mode 2 "Lower hemisphere"	Bridge Pin 1 (U _B) and Pin 8 twice briefly	LED (green) flashes twice
Mode 3, 2 x 360°	Bridge Pin 1 (U _B) and Pin 8 three times briefly	LED (green) flashes three times
Mode 4, X: 0360°, Y: off	Bridge Pin 1 (U _B) and Pin 8 four times briefly	LED (green) flashes four times
Mode 5, Y: 0360°, X: off	Bridge Pin 1 (U _B) and Pin 8 five times briefly	LED (green) flashes five times
Filter setting mode	Bridge Pin 3 (GND) and Pin 8 for 10 s You	Status LED (yellow) steady, after 10 s flashes
	must set a further teach input within 10 s or	
	the device will automatically exit this mode	
24 Hz, default setting	Bridge Pin 3 (GND) and Pin 8 once briefly	LED (yellow) flashes once
15 Hz	Bridge Pin 3 (GND) and Pin 8 twice briefly	LED (yellow) flashes twice
Most effective filter setting	Bridge Pin 3 (GND) and Pin 8 three times briefly	LED (yellow) flashes three times
Factory setting	Bridge Pin 3 (GND) or Pin 1 (UB) and Pin 8 for 15 s	LED flashes fast after 15 s

Note:

Please note that with changing the zero point you also change the start and end point of the measuring range accordingly. For the "Upper hemisphere" and "Lower hemisphere" functions, a zero offset may not be possible because the offset would cause the measuring range to be partially outside the defined range of 0°...±90° or 90...270°. This must also be observed when programming the start and end point.



Function accessories

Type code	Ident no.		Dimension drawing
TX3-Q20L60	6967118	Teach adapter for 8-pin sensors	8 04.5 015 M12x1
USB-2-IOL-0002	6825482	IO-Link Master with integrated USB port	LED: USB-Mini CH1 (C/O) LED: PWR CH2 (DI/DO) IN-DC Error 24