

RI360P0-EQR24M0-IOLX2-H1141 Contactless Encoder with Stainless Steel Housing – IO-Link Premium Line





Technical data

Туре	RI360P0-EQR24M0-IOLX2-H1141
ID	1590978
Measuring principle	Inductive
General data	
Max. Rotational Speed	800 rpm
	Determined with standardized construc- tion, with a steel shaft \emptyset 20 mm, L = 50 mm and reducer \emptyset 20 mm
Starting torque shaft load (radial / axial)	not applicable, because of contactless measuring principle
Measuring range	0360 °
Nominal distance	1.5 mm
Repeat accuracy	≤ 0.01 % of full scale
Linearity deviation	≤ 0.05 % f.s.
Temperature drift	≤ ± 0.003 %/K
Output type	Absolute semi-multiturn
Resolution singleturn	16 bit/65,536 units per revolution
Resolution multiturn	13 bit/8192 revolutions
Number of diagnostic bits	3 Bit
Electrical data	
Operating voltage	1530 VDC
Residual ripple	≤ 10 % U _{ss}
Isolation test voltage	≤ 0.5 kV
Wire breakage/Reverse polarity protec- tion	yes (voltage supply)
Communication protocol	IO-Link

Features

Compact, rugged housing	
Active face, plastic PA12-GF30	
Housing, stainless steel V4A (1.4404)	
Status displayed via LED	
Immune to electromagnetic interference	
16 bits singleturn	
Process value in 32 bit IO-Link telegram	
3 error bits	
16 bits singleturn	
13 bits multiturn	
1530 VDC	
M12 × 1 male connector, 4-pin	

Wiring diagram





Functional principle

The measuring principle of inductive encoders is based on oscillation circuit coupling between the positioning element and the sensor, whereby an output signal is provided proportional to the angle of the positioning element. Turck refers to semimultiturn because the multiturn process data is calculated internally from the number



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Current consumption	< 50 mA
IO-Link	
IO-Link specification	V 1.1
Programming	FDT/DTM
Communication mode	COM 2 (38.4 kBaud)
Process data width	32 bit
Minimum cycle time	3 ms
Function pin 4	IO-Link
Included in the SIDI GSDML	Yes
Mechanical data	
Design	EQR24
Dimensions	81 x 78 x 24 mm
Flange type	Flange without mounting element
Shaft Type	Hollow shaft
Shaft diameter D [mm]	6 6.35 9.525 10 12 12.7 14 15.875 19.05 20
Housing material	Stainless-steel/Plastic, 1.4404 (AISI 316L)/PA12-GF30
Electrical connection	Connector, M12 × 1
Environmental conditions	
Ambient temperature	-25+85 °C
	Acc. to UL approval to +70 °C
Vibration resistance	55 Hz (1 mm)
Vibration resistance (EN 60068-2-6)	20 g; 103000 Hz; 50 cycles; 3 axes
Shock resistance (EN 60068-2-27)	100 g; 11 ms ½ sine; 3 × each; 3 axes
Continuous shock resistance (EN 60068-2-29)	40 g; 6 ms ½ sine; 4000 × each; 3 axes
Protection class	IP68 IP69K
MTTF	138 years acc. to SN 29500 (Ed. 99) 40 °C
Power-on indication	LED, Green
Measuring range display	LED, yellow, yellow flashing
Included in delivery	Adapter sleeve MT-QR24

of single-turn zero passes. Because the sensor does not detect any revolutions when not supplied with power, the plausibility of the multiturn process data is indicated by a diagnostic bit. The rugged sensors are maintenance- and wear-free thanks to the contactless operating principle. They convince through their excellent repeatability, resolution and linearity within a broad temperature range. The innovative technology ensures high immunity to electromagnetic DC and AC fields.



Mounting instructions





Extensive range of mounting accessories for easy adaptation to many different shaft diameters. Based on the functional principle of RLC coupling, the sensor operates absolutely wear-free and is immune to magnetized metal splinters and other interference fields. Wrong installation is hardly possible.

The adjacent figure shows the two separate units, sensor and positioning element. Mounting option A:

First, interconnect positioning element and rotatable shaft. Then place the encoder above the rotating part in such a way that you get a tight and protected unit.

Mounting option B:

Push the encoder on the back site of the shaft and fasten it to the machine. Then clamp the positioning element to the shaft with the bracket.

Mounting option C:

If the positioning element is to be screwed on a rotating machine part and not on a shaft, install first the dummy plug RA8-QR24. Then tie up the bracket. Screw on the encoder via the three bores.

The separately arranged sensor and positioning element inhibit that compensating currents or damaging mechanical loads are transmitted via the shaft to the sensor. In addition, the encoder remains tight and highly protected during its entire lifespan. The accessories enclosed in the delivery help to mount encoder and positioning element at an optimal distance from each other. LEDs indicate the switching status. Optionally, you can use the shields which are included in the accessories to increase the allowed distance between positioning element and sensor.

Status display via LED

green steady: Sensor is operative yellow steady: Positioning element has reached the end of the measuring range. This is indicated by a weaker signal.

yellow flashing: Positioning element is outside the measuring range.

off:

Positioning element is in the measuring range



Accessories





Accessories

